
Stable Adaptive Neural Network Control

Neural Information Processing

Adaptive Neural Network Control of Robotic Manipulators

Neural Network-Based State Estimation of Nonlinear Systems

System Identification and Adaptive Control

Applications of Neural Networks in High Assurance Systems

Modeling and Control of Complex Systems

Adaptive Sliding Mode Neural Network Control for Nonlinear Systems

Neural Network-Based Adaptive Control of Uncertain Nonlinear Systems

Modeling, Control and Coordination of Helicopter Systems

Advances in Neural Networks - ISNN 2006

CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume XIII

Stable Adaptive Neural Network Control

Advances in Neural Networks - ISNN 2007

Nature-Inspired Computing: Concepts, Methodologies, Tools, and Applications

Proceedings of ELM-2017

Identification and Adaptive Control for Nonlinear Systems and Applications
Intelligent Control Design and MATLAB Simulation
Adaptive Neural Network Control of Robotic Manipulators
Advances in Neural Networks- ISNN 2013
Advances in Neural Networks
Autonomous Mobile Robots
Robust Adaptive Control for Fractional-Order Systems with Disturbance and Saturation
Advances in Neural Networks - ISNN 2015
Applied Artificial Higher Order Neural Networks for Control and Recognition
Advances in Neural Networks - ISNN 2005
Neural Network Control of Nonlinear Discrete-Time Systems
Radial Basis Function (RBF) Neural Network Control for Mechanical Systems
Application of Neural Networks to Adaptive Control of Nonlinear Systems
Deterministic Learning Theory for Identification, Recognition, and Control
Wireless Algorithms, Systems, and Applications
Adaptive Neural Network Control of Robotic Manipulators
Stable Adaptive Neural Network Control
Mechanical Engineers' Handbook, Volume 2
Advances in Neural Networks - ISNN 2006

Stable Adaptive Control and Estimation for Nonlinear Systems
Modern Adaptive Fuzzy Control Systems
Radial Basis Function (RBF) Neural Network Control for Mechanical Systems
Advances in Neural Networks -- ISSN 2011
Artificial Neural Networks – ICANN 2009
Active Vibration Control and Stability Analysis of Flexible Beam Systems

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SANTANA MCKEE

Neural Information Processing IGI Global
This volume is part of the two-volume proceedings of the 19th International Conference on Artificial Neural Networks (ICANN 2009), which was held in Cyprus during September 14–17, 2009. The ICANN conference is an annual meeting sponsored by the European Neural Network Society (ENNS), in cooperation

with the International Neural Network Society (INNS) and the Japanese Neural Network Society (JNNS). ICANN 2009 was technically sponsored by the IEEE Computational Intelligence Society. This series of conferences has been held annually since 1991 in various European countries and covers the field of neurocomputing, learning systems and related areas. Artificial neural networks provide an information-processing structure inspired by biological nervous systems. They consist of a large number

of highly interconnected processing elements, with the capability of learning by example. The field of artificial neural networks has evolved significantly in the last two decades, with active participation from diverse fields, such as engineering, computer science, mathematics, artificial intelligence, system theory, biology, operations research, and neuroscience. Artificial neural networks have been widely applied for pattern recognition, control, optimization, image processing, classification, signal processing, etc.

Adaptive Neural Network Control of Robotic Manipulators World Scientific Series In Robotics And Intelligent Systems

This book constitutes the proceedings of the 12th International Conference on

Wireless Algorithms, Systems, and Applications, WASA 2017, held in Guilin, China, in June 2017. The 70 full papers and 9 short papers presented in this book were carefully reviewed and selected from 238 submissions. The papers cover various topics such as cognitive radio networks; wireless sensor networks; cyber-physical systems; distributed and localized algorithm design and analysis; information and coding theory for wireless networks; localization; mobile cloud computing; topology control and coverage; security and privacy; underwater and underground networks; vehicular networks; internet of things; information processing and data management; programmable service interfaces; energy-efficient algorithms; system and

protocol design; operating system and middle-ware support; and experimental test-beds, models and case studies.

Neural Network-Based State Estimation of Nonlinear Systems Springer Science & Business Media

This Encyclopedia of Control Systems, Robotics, and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS, which is an integrated compendium of twenty one Encyclopedias. This 22-volume set contains 240 chapters, each of size 5000-30000 words, with perspectives, applications and extensive illustrations. It is the only publication of its kind carrying state-of-the-art knowledge in the fields of Control Systems, Robotics, and Automation and is aimed, by virtue of the several applications, at the

following five major target audiences: University and College Students, Educators, Professional Practitioners, Research Personnel and Policy Analysts, Managers, and Decision Makers and NGOs.

System Identification and Adaptive Control CRC Press

A treatise on investigating tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation Robust Adaptive Control for Fractional-Order Systems, with Disturbance and Saturation provides the reader with a good understanding on how to achieve tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties,

external disturbance, and input saturation. Although some texts have touched upon control of fractional-order systems, the issues of input saturation and disturbances have rarely been considered together. This book offers chapter coverage of fractional calculus and fractional-order systems; fractional-order PID controller and fractional-order disturbance observer; design of fractional-order controllers for nonlinear chaotic systems and some applications; sliding mode control for fractional-order nonlinear systems based on disturbance observer; disturbance observer based neural control for an uncertain fractional-order rotational mechanical system; adaptive neural tracking control for uncertain fractional-order chaotic systems subject to input saturation and

disturbance; stabilization control of continuous-time fractional positive systems based on disturbance observer; sliding mode synchronization control for fractional-order chaotic systems with disturbance; and more. Based on the approximation ability of the neural network (NN), the adaptive neural control schemes are reported for uncertain fractional-order nonlinear systems Covers the disturbance estimation techniques that have been developed to alleviate the restriction faced by traditional feedforward control and reject the effect of external disturbances for uncertain fractional-order nonlinear systems By combining the NN with the disturbance observer, the disturbance observer based adaptive neural control schemes have been

studied for uncertain fractional-order nonlinear systems with unknown disturbances. Consider, together, the issue of input saturation and the disturbance for the control of fractional-order nonlinear systems in the presence of system uncertainty, external disturbance, and input saturation. Robust Adaptive Control for Fractional-Order Systems, with Disturbance and Saturation can be used as a reference for the academic research on fractional-order nonlinear systems or used in Ph.D. study of control theory and engineering. *Applications of Neural Networks in High Assurance Systems* Springer Science & Business Media

Comprehension of complex systems comes from an understanding of not only the behavior of constituent elements but

how they act together to form the behavior of the whole. However, given the multidisciplinary nature of complex systems, the scattering of information across different areas creates a chaotic situation for those trying to understand possible solutions and applications. *Modeling and Control of Complex Systems* brings together a number of research experts to present some of their latest approaches and future research directions in a language accessible to system theorists. Contributors discuss complex systems such as networks for modeling and control of civil structures, vehicles, robots, biomedical systems, fluid flow systems, and home automation systems. Each chapter provides theoretical and methodological descriptions of a specific

application in the control of complex systems, including congestion control in computer networks, autonomous multi-robot docking systems, modeling and control in cancer genomics, and backstepping controllers for stabilization of turbulent flow PDEs. With this unique reference, you will discover how complexity is dealt with in different disciplines and learn about the latest methodologies, which are applicable to your own specialty. The balanced mix of theory and simulation presented by *Modeling and Control of Complex Systems* supplies a strong vehicle for enlarging your knowledge base a fueling future advances and incredible breakthroughs.

Modeling and Control of Complex Systems Springer Nature

Radial Basis Function (RBF) Neural Network Control for Mechanical Systems is motivated by the need for systematic design approaches to stable adaptive control system design using neural network approximation-based techniques. The main objectives of the book are to introduce the concrete design methods and MATLAB simulation of stable adaptive RBF neural control strategies. In this book, a broad range of implementable neural network control design methods for mechanical systems are presented, such as robot manipulators, inverted pendulums, single link flexible joint robots, motors, etc. Advanced neural network controller design methods and their stability analysis are explored. The book provides readers with the fundamentals of neural

network control system design. This book is intended for the researchers in the fields of neural adaptive control, mechanical systems, Matlab simulation, engineering design, robotics and automation. Jinkun Liu is a professor at Beijing University of Aeronautics and Astronautics.

Adaptive Sliding Mode Neural Network Control for Nonlinear Systems Springer Science & Business Media

The three volume set LNCS 3496/3497/3498 constitutes the refereed proceedings of the Second International Symposium on Neural Networks, ISSN 2005, held in Chongqing, China in May/June 2005. The 483 revised papers presented were carefully reviewed and selected from 1.425 submissions. The papers are organized in topical sections

on theoretical analysis, model design, learning methods, optimization methods, kernel methods, component analysis, pattern analysis, systems modeling, signal processing, image processing, financial analysis, control systems, robotic systems, telecommunication networks, incidence detection, fault diagnosis, power systems, biomedical applications, industrial applications, and other applications.

Neural Network-Based Adaptive Control of Uncertain Nonlinear Systems Springer

The two volume set LNCS 5263/5264 constitutes the refereed proceedings of the 5th International Symposium on Neural Networks, ISSN 2008, held in Beijing, China in September 2008. The 192 revised papers presented were carefully reviewed and selected from a

total of 522 submissions. The papers are organized in topical sections on computational neuroscience; cognitive science; mathematical modeling of neural systems; stability and nonlinear analysis; feedforward and fuzzy neural networks; probabilistic methods; supervised learning; unsupervised learning; support vector machine and kernel methods; hybrid optimisation algorithms; machine learning and data mining; intelligent control and robotics; pattern recognition; audio image processing and computer vision; fault diagnosis; applications and implementations; applications of neural networks in electronic engineering; cellular neural networks and advanced control with neural networks; nature inspired methods of high-dimensional

discrete data analysis; pattern recognition and information processing using neural networks.

Modeling, Control and Coordination of Helicopter Systems Springer

"Applications of Neural Networks in High Assurance Systems" is the first book directly addressing a key part of neural network technology: methods used to pass the tough verification and validation (V&V) standards required in many safety-critical applications. The book presents what kinds of evaluation methods have been developed across many sectors, and how to pass the tests. A new adaptive structure of V&V is developed in this book, different from the simple six sigma methods usually used for large-scale systems and different from the theorem-based

approach used for simplified component subsystems.

Advances in Neural Networks - ISNN 2006 John Wiley & Sons

This book contains some selected papers from the International Conference on Extreme Learning Machine (ELM) 2017, held in Yantai, China, October 4-7, 2017. The book covers theories, algorithms and applications of ELM. Extreme Learning Machines (ELM) aims to enable pervasive learning and pervasive intelligence. As advocated by ELM theories, it is exciting to see the convergence of machine learning and biological learning from the long-term point of view. ELM may be one of the fundamental 'learning particles' filling the gaps between machine learning and biological learning (of which activation

functions are even unknown). ELM represents a suite of (machine and biological) learning techniques in which hidden neurons need not be tuned: inherited from their ancestors or randomly generated. ELM learning theories show that effective learning algorithms can be derived based on randomly generated hidden neurons (biological neurons, artificial neurons, wavelets, Fourier series, etc) as long as they are nonlinear piecewise continuous, independent of training data and application environments. Increasingly, evidence from neuroscience suggests that similar principles apply in biological learning systems. ELM theories and algorithms argue that "random hidden neurons" capture an essential aspect of biological learning mechanisms as well

as the intuitive sense that the efficiency of biological learning need not rely on computing power of neurons. ELM theories thus hint at possible reasons why the brain is more intelligent and effective than current computers. This conference will provide a forum for academics, researchers and engineers to share and exchange R&D experience on both theoretical studies and practical applications of the ELM technique and brain learning. It gives readers a glance of the most recent advances of ELM.

CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume XIII Springer Nature

Includes a solution manual for problems. Provides MATLAB code for examples and solutions. Deals with robust systems in both theory and practice.

Stable Adaptive Neural Network Control CRC Press

Identification and Adaptive Control for Nonlinear Systems and Applications: Applied Mathematics in Control Engineering introduces nonlinear systems concepts, system analysis, system control methods and applications in various fields. The major contribution of the book includes: (1) The basic concepts of nonlinear systems stability analysis and nonlinear systems control method. (2) The stability analysis of complex nonlinear system with adaptive neural networks control. (3) The nonlinear systems adaptive sliding mode controller design of complex nonlinear systems. (4) Some industrial application. The book gives an introduction to basic nonlinear systems architectures for

adaptive control methods. Emphasis is placed on the mathematical analysis of these systems, on methods of controlling them for adaptive control and on their application to practical engineering problems in such areas as aircraft path planning. This book enables audience to understand the basic architectures of control science and engineering, and to master classical and advanced design method for nonlinear system. Introduces nonlinear systems concepts, system analysis, system control methods and applications in various fields Presents basic concepts of nonlinear systems stability analysis and nonlinear systems control method Offers practical examples

Advances in Neural Networks - ISNN 2007 Academic Press

In recent years, Higher Order Neural Networks (HONNs) have been widely adopted by researchers for applications in control signal generating, pattern recognition, nonlinear recognition, classification, and prediction of control and recognition scenarios. Due to the fact that HONNs have been proven to be faster, more accurate, and easier to explain than traditional neural networks, their applications are limitless. Applied Artificial Higher Order Neural Networks for Control and Recognition explores the ways in which higher order neural networks are being integrated specifically for intelligent technology applications. Emphasizing emerging research, practice, and real-world implementation, this timely reference publication is an essential reference

source for researchers, IT professionals, and graduate-level computer science and engineering students.

Nature-Inspired Computing: Concepts, Methodologies, Tools, and Applications

Springer

Radial Basis Function (RBF) Neural Network Control for Mechanical Systems is motivated by the need for systematic design approaches to stable adaptive control system design using neural network approximation-based techniques. The main objectives of the book are to introduce the concrete design methods and MATLAB simulation of stable adaptive RBF neural control strategies. In this book, a broad range of implementable neural network control design methods for mechanical systems are presented, such as robot

manipulators, inverted pendulums, single link flexible joint robots, motors, etc. Advanced neural network controller design methods and their stability analysis are explored. The book provides readers with the fundamentals of neural network control system design. This book is intended for the researchers in the fields of neural adaptive control, mechanical systems, Matlab simulation, engineering design, robotics and automation. Jinkun Liu is a professor at Beijing University of Aeronautics and Astronautics.

Proceedings of ELM-2017 Springer
Introduction; Mathematical background; Dynamic modelling of robots; Structured network modelling of robots; Adaptive neural network control of robots; Neural network model reference adaptive

control; Flexible joint robots; task space and force control; Bibliography; Computer simulation; Simulation software in C.

Identification and Adaptive Control for Nonlinear Systems and Applications
World Scientific

The volume LNCS 9377 constitutes the refereed proceedings of the 12th International Symposium on Neural Networks, ISSN 2015, held in Jeju, South Korea in October 2015. The 55 revised full papers presented were carefully reviewed and selected from 97 submissions. These papers cover many topics of neural network-related research including intelligent control, neurodynamic analysis, memristive neurodynamics, computer vision, signal processing, machine learning, and

optimization.

Intelligent Control Design and MATLAB Simulation Springer Science & Business Media

This book investigates the ability of a neural network (NN) to learn how to control an unknown (nonlinear, in general) system, using data acquired online, that is during the process of attempting to exert control. Two algorithms are developed to train the neural network for real-time control applications. The first algorithm is known as Learning by Recursive Least Squares (LRLS) algorithm and the second algorithm is known as Integrated Gradient and Least Squares (IGLS) algorithm. The ability of these algorithms for training the NN controller for real-time control is demonstrated on practical

applications and the local convergence and stability requirements of these algorithms are analysed. In addition, network topology, learning algorithms (particularly supervised learning) and neural network control strategies including a new classification system for them, are presented.

Adaptive Neural Network Control of Robotic Manipulators Springer

This book offers a comprehensive introduction to intelligent control system design, using MATLAB simulation to verify typical intelligent controller designs. It also uses real-world case studies that present the results of intelligent controller implementations to illustrate the successful application of the theory. Addressing the need for systematic design approaches to

intelligent control system design using neural network and fuzzy-based techniques, the book introduces the concrete design method and MATLAB simulation of intelligent control strategies; offers a catalog of implementable intelligent control design methods for engineering applications; provides advanced intelligent controller design methods and their stability analysis methods; and presents a sample simulation and Matlab program for each intelligent control algorithm. The main topics addressed are expert control, fuzzy logic control, adaptive fuzzy control, neural network control, adaptive neural control and intelligent optimization algorithms, providing several engineering application examples for each method.

Advances in Neural Networks- ISNN 2013 Springer Science & Business Media
It has long been the goal of engineers to develop tools that enhance our ability to do work, increase our quality of life, or perform tasks that are either beyond our ability, too hazardous, or too tedious to be left to human efforts. Autonomous mobile robots are the culmination of decades of research and development, and their potential is seemingly unlimited. Roadmap to the Future Serving as the first comprehensive reference on this interdisciplinary technology, *Autonomous Mobile Robots: Sensing, Control, Decision Making, and Applications* authoritatively addresses the theoretical, technical, and practical aspects of the field. The book examines in detail the key components that form

an autonomous mobile robot, from sensors and sensor fusion to modeling and control, map building and path planning, and decision making and autonomy, and to the final integration of these components for diversified applications. Trusted Guidance A duo of accomplished experts leads a team of renowned international researchers and professionals who provide detailed technical reviews and the latest solutions to a variety of important problems. They share hard-won insight into the practical implementation and integration issues involved in developing autonomous and open robotic systems, along with in-depth examples, current and future applications, and extensive illustrations. For anyone involved in researching, designing, or deploying

autonomous robotic systems, Autonomous Mobile Robots is the perfect resource.

Advances in Neural Networks

Springer

The three-volume set LNCS 6675, 6676 and 6677 constitutes the refereed proceedings of the 8th International Symposium on Neural Networks, ISNN 2011, held in Guilin, China, in May/June 2011. The total of 215 papers presented in all three volumes were carefully reviewed and selected from 651 submissions. The contributions are structured in topical sections on computational neuroscience and cognitive science; neurodynamics and complex systems; stability and

convergence analysis; neural network models; supervised learning and unsupervised learning; kernel methods and support vector machines; mixture models and clustering; visual perception and pattern recognition; motion, tracking and object recognition; natural scene analysis and speech recognition; neuromorphic hardware, fuzzy neural networks and robotics; multi-agent systems and adaptive dynamic programming; reinforcement learning and decision making; action and motor control; adaptive and hybrid intelligent systems; neuroinformatics and bioinformatics; information retrieval; data mining and knowledge discovery; and natural language processing.